



Robotic Cleaner DRC300

Maximum cleaning area 600m²

*two BL1860B in parallel





Mapping using LiDAR sensor (2D) and Camera sensor





Equipped with LiDAR sensor (2D) and Camera sensor, the cleaner can map and memorize the rooms to clean.

LiDAR module (LiDAR sensor)

Grasping and mapping the two-dimensional shape of rooms with a rotating laser displacement gauge.



TOTA

Vision camera (Camera sensor)

Grasping the characteristic shape of ceilings and walls, and memorizing them by connecting them with the self-location of the Robotic cleaner to increase mapping precision.



Mapping

Equipped with LiDAR sensor (2D) and Camera sensor, the cleaner can map and memorize the rooms to clean. Then, based on the map, the cleaner can track an optimal route for efficient cleaning.





Due to Bottom plate and Side brushes removable without tool



Can be attached/ detached from the top of the machine.



RF remote controller

Start point button –	0 0
Location beacon – buzzer/light button	N
Shift button -	-

makita



- Action buttons Start/stop button
- Sound ON/OFF
- button
- Vacuum fan **ON/OFF** button

Free cleaning

In "Free cleaning" mode,

cleaning can be started

registering room information

immediately without

Large carry handle



m² $\mathbf{\hat{n}}$ The area where the coverage rate can be 95% or more within the operating time [with two BL1860B batteries]



capacity Small debri Large debris

small debris into upper compartment.

Power brush picks up large debris into lower compartment.

Dual compartment structure - one for small debris, the other for large debris - is ideal for commercial use.

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